

Mj Construcción E Ingeniería

M Lipman

New Approaches to the Archaeology of Beekeeping David Wallace-Hare, 2022-02-17 17 papers take a holistic view of beekeeping archaeology (including honey, wax, associated products, hive construction, and trade) in one large interconnected geographic region, the Mediterranean, central Europe, and the Atlantic Façade. The book serves as a handbook for current and future researchers considering the archaeology of beekeeping.

Applied Study of Cultural Heritage and Clays J. L. Pérez Rodríguez, 2003

Ingeniería y construcción , 1929

Ingeniería internacional. Edición de construcción , 1919

Diario Oficial Colombia, 1972

IX Congreso Nacional de Propiedades Mecánicas de Sólidos. Diego Gómez García, 2004 Trata diversos aspectos relacionados con las propiedades mecánicas de los sólidos y sus posibles modificaciones, el estudio de los mecanismos que las justifican y su modelización. Todo ello, tanto desde el punto de vista fundamental, como aplicado y referido a diferentes materiales: metales, cerámica, polímeros...

Diario de las sesiones de Cortes , 1890

Vías de comunicación romanas en Castilla-La Mancha Gregorio Carrasco Serrano, 2016-06-22 En la presente obra se lleva a cabo un estudio de las comunicaciones romanas en el territorio de Castilla-La Mancha, teniendo en cuenta las últimas investigaciones al respecto llevadas a cabo. Así pues, es objeto de análisis la viaria de la provincia de Albacete, así como del ámbito territorial de Ciudad Real y de Toledo. Igualmente se realiza un estado de la cuestión de las comunicaciones romanas de las provincias de Cuenca y Guadalajara. También se presta atención a la circulación monetaria y al comercio del lapis specularis en relación a las vías romanas del territorio, contemplándose asimismo aspectos determinantes de la red viaria como son los miliarios y los puentes romanos de este ámbito de la Meseta meridional de Hispania.

Libros en venta en Hispanoamérica y España , 1993

Manipuladores paralelos: síntesis, análisis y aplicaciones Quintero Riaza, Hector Fabio, Mejía Calderón, Luz Adriana, Holguín, Germán, Díaz Rodríguez, Miguel Angel, Herrera López, Marlon Jahir, Mesa, Carlos Andrés, Daraviña Peña, Giancarlo, 2022-07-29 Debido a necesidades de la industria como incrementar la producción y realizar tareas peligrosas para

el hombre, se desarrollaron mecanismos automatizados que realizan operaciones de producción de manera más rápida, segura y económica. A estos mecanismos automatizados se les llamó robots. Los robots fueron diseñados y construidos desde hace varias décadas con el objetivo de prestar servicios a los humanos en tareas repetitivas; en la industria, los robots se emplean para elaborar trabajos de pintura, soldadura, ensamble de piezas, entre otros. En el área aeroespacial, han sido utilizados como rescatadores de satélites, en la recolección de muestras, en la exploración de terrenos y para labores de mantenimiento de las estaciones espaciales. Muchas aplicaciones que hace décadas se consideraban imposibles de realizar, hoy son realidad. Existe una gran variedad de familias de robots. Los más utilizados en la industria son los llamados manipuladores seriales y manipuladores paralelos. Los primeros, mucho más utilizados y estudiados que los segundos, especialmente en lo que respecta a su fabricación y su control [1]. Sin embargo, esta configuración en serie supone también una pérdida de dinamismo: cada accionamiento tiene que llevar el peso de los accionamientos que le siguen. Son configuraciones con grandes masas en movimiento, por lo que resulta complicado obtener velocidades altas de trabajo. En los últimos años se ha presentado un creciente interés de los investigadores en los manipuladores paralelos debido a sus ventajas sobre sus contrapartes seriales, esto se debe a que sin importar que los manipuladores paralelos tengan actuadores fijos en su estructura, o que se muevan muy próximos a ella, ninguno de los actuadores debe llevar el peso de otro cuando realiza un movimiento, todos ellos conectan la estructura fija con el cabezal de trabajo o la herramienta final. Por estas características las cadenas cinemáticas y los sistemas de accionamiento pueden ser más pequeños, lo que permite aumentar la masa útil que se puede mover con el manipulador

Ingeniería internacional ,1922

Revista minera, metalurgica y de ingeniería ,1885

Ingeniería ,1918

Sustainable Use of Traditional Geomaterials in Construction Practice ,2016-08-02 Geomaterials derived from the Earth's crust and used in construction after appropriate processing are among the earliest raw materials exploited, processed and used by humans. Their numerous functional properties include accessibility, workability and serviceability, and these are explored within this volume. In modern society, sustainable use of raw materials, specifically those exploited in large volumes such as geomaterials for construction, raises questions of reducing extraction of primary resources and thus minimizing impacts on natural systems, and also employment of materials and technologies to lower emissions of deleterious substances into the atmosphere. This will be possible only if we fully understand the properties, processing and mode of use of traditional geomaterials. Although most of the papers within this volume were written by geologists, the contributions will also be of interest to those working in cultural heritage, monument conservation, civil engineering and architecture.

Actas del Segundo Congreso Nacional de Historia de la Construcción Fernando Bores Gamundi, Instituto Juan de

Herrera (Madrid, Spain), Centro de Estudios Históricos de Obras Públicas y Urbanismo (Spain), 1998

Las estadísticas del sector construcción en Costa Rica Marie Eve Mulquin, 1981

Ingeniería internacional , 1920

Produccion Revista de agricultura, industria e ingeniería , 1923

Ingeniería internacional , 1920

Boletín de obras públicas Cuba. Secretaría de Obras Públicas, 1927

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