

# Proyecto De Mano Robotica Casera

**Oliver García López**

*INEÁPOLI. LOS HEREDEROS DEL BARRIO ANIA ZAERA*,2023-05-19 ¿Te atreves a imaginar el mundo dentro de 200 años? Tras el Cataclismo que ponga fin a la civilización tal como la conocemos, Ineápoli será el último bastión de la humanidad. Con el interior de las murallas dividido por una frontera, los recursos en decrecimiento, las defensas exteriores fallando y la naturaleza acechando a los supervivientes, Victoria, una urbanita rebelde, y Luca, un cortés con un don único, encontrarán en su amistad y en un inesperado romance la fuerza para desafiar al sistema que los separa. Apoyándose en un grupo de jóvenes que dejarán sus diferencias a un lado, lucharán por cambiar el orden establecido, llegando hasta el final para acabar con las misteriosas desapariciones. ¿Podrá cambiar el destino de toda una ciudad y permanecer juntos?

*Reconstrucción puesta en funcionamiento y mejora de mano robot* Eduardo Enrique Oliveros Acosta,2018-12-04 Este libro describe de forma clara, el proceso de reingeniería de mano robótica de cuatro dedos UMNG que se realizó durante este proyecto de investigación, para esto se presentan de una manera clara la información correspondiente a manos robóticas en general, así como mecanismos y sistemas de manipulación de objetos. Se presenta de manera general descripción de la mano UMNG, mostrando así proceso de construcción y resultados obtenidos con su elaboración en el 2002. Se desea Mostrar de manera detallada proceso de reingeniería realizado, obteniendo resultados favorables, mostrando así sistema mecánico virtual y en simulación, interfaz de comunicación y visualización de movimiento dentro de entorno virtual, también se expone validación de resultados en movimiento.

*Diseño y construcción de mano robótica prensil con fines prostéticos* Gustavo Xavier Zapata Villacís,2015 La mano es sin duda alguna una herramienta indispensable para incontables actividades que desarrollamos cotidianamente. Cuando una persona pierde esta extremidad, ocasionado por alguna enfermedad o un accidente, pierde también la posibilidad de desarrollar estas actividades de la forma acostumbrada. Es por esto por lo que existe la motivación de desarrollar este tipo de proyectos, con el fin de facilitar el proceso de rehabilitación y poder brindar comodidad en la cotidianidad de las personas afectadas. Con el fin de estudiar un poco más a profundidad el diseño de las manos robóticas se desarrolla en el siguiente proyecto la construcción de una mano prensil funcional con un diseño nuevo teniendo en cuenta los resultados y recomendaciones obtenidos en proyectos anteriores. Como innovación se utiliza una silicona que ayuda a simular el efecto de deformación y fricción de la piel humana. También se prueba una nueva unión interfalángica que simula el efecto de los

tendones que a la vez facilitan el proceso de ensamble de la mano. También se facilita la variación de los valores de rigidez de estas uniones con el fin de mejorar otros tipos de agarre aparte de la prensión gruesa cilíndrica y esférica. El proyecto sigue los siguientes pasos: -Análisis y estudio del estado del arte de las manos robóticas prensil y soluciones comerciales. - Construcción computacional del nuevo diseño propuesto y simulación de la cinemática de este. -Diseño de subactuación de la mano con el fin de reducir el número de actuadores y aumentar el número de grados de libertad de los dedos. -Construcción de un prototipo de la mano con implementación de actuadores y un circuito que facilita la experimentación para comprobar la sujeción de la mano objetos de distintas formas y pesos. Gracias al prototipo construido es posible comprobar la funcionalidad de la mano al efectuar las sujeciones. También se obtiene un modelo CAD que permita la adaptación del diseño a diferentes dimensiones de la mano.

Análisis y diseño de un prototipo de una mano robótica con catorce grados de libertad, capaz de ser dirigida a través de internet en tiempo real Jhosep Edgar Andrei Hower Ceballos, Carlos Andrés Correa Arroyave, Carlos Uriel Pareja Rodríguez, 2012 Introduccion: En el mundo de la robótica se encuentran muchos trabajos en el área de las manos robóticas muchas de las cuales se encuentran fuera del alcance de la gente del común o de las pequeñas empresas debido a sus altos costos, el equipo especializado que se necesita y la falta de proveedores en el país, lo que puede llegar a limitar el desarrollo y aplicación de este tipo de tecnologías en nuestra región. El costo del robot depende de sus especificaciones, capacidad, flexibilidad y tecnología. Además de los factores complementarios como equipos periféricos, dispositivos de fijación y señalización, puesta en marcha y puesta a punto, servicio postventa, entrenamiento y mantenimiento. Usualmente una solución completa puede estar por el orden de 30.000 y 70.000 dólares, sin embargo, hay industrias que por su tamaño requieren de más recursos<sup>1</sup>. Este proyecto pretende abrir una ventana para el desarrollo de estas tecnologías en nuestra región entregando un análisis y diseño de una mano robótica que sirva como base para futuras investigaciones en este campo. En la actualidad en las diferentes universidades del eje cafetero que poseen el programa de Ingeniería de sistemas (ver tabla 1) no se encuentra ninguna que posea en su pensum la materia de Robótica, si algunas materias allegadas a este campo, pero no una que esté enfocada en ella.

**Modelación y evaluación de mano robótica con estrategia de agarre** Felipe Carlos Benavides Pantoja, Universidad de Concepción (Chile). Facultad de Ingeniería. Departamento de Ingeniería Eléctrica, 2008

*Diseño e implementación de una mano robótica antropomórfica controlada mediante guante sensorizado* Omar H. Flores Mamani, 2011

**Manos Robóticas Protésicas** Amaury Pino, 2020-12-28 Este libro consolida el uso de tecnologías disruptivas, realizando una combinación de hardware y software bajo licencia, con el uso de tecnologías y recursos de código abierto (Open Source), para el desarrollo de manos robóticas electromiográficas. La propuesta describe un desarrollo experimental de mano

robótica innovadora y sencilla a la vez, realizada mediante el diseño asistido por computadoras (CAD), utilizando microcontroladores programados bajo el entorno integrado de desarrollo de Arduino (IDE), impresión 3D y sensores electromiográficos superficiales. Se creó durante el proyecto elementos móviles y estáticos modelados por deposición fundida (FDM), generando un dispositivo asequible y accesible para personas con amputación. Este tipo de propuestas representan una esperanza para el 90% de las personas amputadas que actualmente viven sin acceso a ningún tipo de dispositivos protésicos. Este libro es una lectura esencial para aquellos que deseen contribuir en el diseño de propuestas de bajo costo y funcionales, para atender la creciente demanda de dispositivos protésicos robóticos en el mundo.

Proyecto Robots, 2 Primaria ,2017

Mano robótica Oliver García López,2018

Proyectos 2, material del alumno, proyecto C-2, tengo un robot Miguel Ángel Gautier Jiménez,Mónica Roldán Écija,2017-05

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