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M. H. Hamza,International Association of Science and Technology for Development

The Control of Multiple Unmanned Aerial Vehicles Mingyang Xie,Jiangbo Jia,Weizhen Wang,2025-12-01 The Control of Multiple Unmanned Aerial Vehicles: Synthesis, Functionalization to Applications provides readers with a unified framework to address the challenges of multi-UAV target encirclement tracking control. This is achieved by comprehensively integrating the concepts of dynamic modelling, state and disturbance estimation, guidance law design, distributed control, obstacle avoidance and reinforcement learning-based formation tracking control with multi-UAV encirclement tracking systems. The book provides practical insight and solutions to the challenges of multi-UAV use, including limited sensing, communication constraint, wind disturbances and obstacle and collision avoidance, enabling readers to effectively apply the concepts to their work or research. Cutting-edge control techniques and advanced theories are explored, including robust distributed control, adaptive neural network approximation, reinforcement learning and multi-agent systems, presenting readers with state-of-the-art methodologies from which to develop practical applications of UAV formation. Each guidance and control method presented in the book is accompanied by a thorough comprehensive analysis to ensure that each is theoretically grounded. The book ensures transparency by providing open-access simulation codes, allowing readers to easily access and reproduce presented results. - The Control of Multiple Unmanned Aerial Vehicles (UAVs) fills a gap in the existing literature by providing solutions to the practical challenges of operating multiple unmanned aerial vehicles (UAVs) - Theoretical concepts are systematically integrated with practical solutions for meeting the challenges of guidance, control and obstacle avoidance in multi-UAV target tracking systems under different constraints - Readers are guided through the development of mathematical methodologies for state observer, guidance law design and obstacle avoidance problems associated with multi-UAV target encirclement tracking systems - Advanced methodologies for cooperative control of UAVs are described and open-access simulation codes are provided allowing readers to easily access and reproduce presented results and ensuring transparency

Analysis and Control for Fractional-order Systems Yonggui Kao,Changhong Wang,Hongwei Xia,Yue Cao,2024-07-07 This book focuses on the applications of various types of fractional-order differential equations. The authors present their

latest research results. This book for the first time introduces the concept of general fractional chaotic systems and their synchronisation, investigates the synchronisation of a fractional coupled reaction-diffusion system using a sliding mode control approach, and considers the impacts of fear and prey escape on a fractional-order prey-predator system with Beddington-DeAngelis functional response. Authors believe that these recent research results can promote the applications of fractional-order differential equations in diverse areas. The book will be attractive to researchers in various fields of mathematics, biomathematics and engineering. Graduate students in related fields may also find this book useful.

Understanding and Bridging the Gap between Neuromorphic Computing and Machine Learning, volume II Huajin Tang, Lei Deng, Kaushik Roy, 2024-08-26 Towards the long-standing dream of artificial intelligence, two solution paths have been paved: (i) neuroscience-driven neuromorphic computing; (ii) computer science-driven machine learning. The former targets at harnessing neuroscience to obtain insights for brain-like processing, by studying the detailed implementation of neural dynamics, circuits, coding and learning. Although our understanding of how the brain works is still very limited, this bio-plausible way offers an appealing promise for future general intelligence. In contrast, the latter aims at solving practical tasks typically formulated as a cost function with high accuracy, by eschewing most neuroscience details in favor of brute force optimization and feeding a large volume of data. With the help of big data (e.g. ImageNet), high-performance processors (e.g. GPU, TPU), effective training algorithms (e.g. artificial neural networks with gradient descent training), and easy-to-use design tools (e.g. Pytorch, Tensorflow), machine learning has achieved superior performance in a broad spectrum of scenarios. Although acclaimed for the biological plausibility and the low power advantage (benefit from the spike signals and event-driven processing), there are ongoing debates and skepticisms about neuromorphic computing since it usually performs worse than machine learning in practical tasks especially in terms of the accuracy.

Advanced Attitude Control of Satellite Bing Xiao, Zhaoyue Chen, Jingwen Xu, Lu Cao, 2024-07-02 This book focuses on the high-accuracy attitude control system design and approaches for satellite with modeling error including system uncertainties, actuator faults, and disturbances. It presents a systematically and almost self-contained description of the many facets of envisaging, designing, implementing, or experimentally exploring modeling error compensation-based attitude control of satellites. The advanced treatment of practical issues in satellite attitude compensation control is one of the major features of the book, which is particularly suited for readers who are interested to learn the latest solutions in attitude control system design of satellites. The book intends to provide a unified platform for understanding and applicability of the modeling error compensation-based attitude control for different purposes in aerospace engineering and some related fields. It can benefit researchers, engineers, and graduate students in the fields of attitude control of satellites and other unmanned systems, aerospace engineering, etc.

Intelligent Computer Mathematics Christoph Benzmüller, Bruce Miller, 2020-07-17 This book constitutes the refereed

proceedings of the 13th International Conference on Intelligent Computer Mathematics, CICM 2020, held in Bertinoro, Italy, in July 2020*. The 15 full papers, 1 invited paper and 2 abstracts of invited papers presented were carefully reviewed and selected from a total of 35 submissions. The papers focus on advances in automated theorem provers and formalization, computer algebra systems and their libraries, and applications of machine learning, among other topics. * The conference was held virtually due to the COVID-19 pandemic.

Medical Image Computing and Computer Assisted Intervention - MICCAI 2025 James C. Gee, Daniel C. Alexander, Jaesung Hong, Juan Eugenio Iglesias, Carole H. Sudre, Archana Venkataraman, Polina Golland, Jong Hyo Kim, Jinah Park, 2025-09-20 The 16-volume set LNCS 15960 - 15975 constitutes the refereed proceedings of the 28th International Conference on Medical Image Computing and Computer Assisted Intervention, MICCAI 2025, which took place in Daejeon, South Korea, during September 23-27, 2025. The total of 1027 papers included in the proceedings was carefully reviewed and selected from 3447 submissions. They were organized in topical parts as follows: Part I, LNCS Volume 15960: Multimodal Fusion and Contextual Reasoning in Medical Imaging Part II, LNCS Volume 15961: Surgical Navigation, Scene Understanding, and Video Modeling Part III, LNCS Volume 15962: Learning and Augmented Reality for Surgical and Endoscopic Applications (I) Part IV, LNCS Volume 15963: Learning and Augmented Reality for Surgical and Endoscopic Applications (II) Part V, LNCS Volume 15964: Graph-Based Methods in Medical Imaging Part VI, LNCS Volume 15965: Datasets and Methods for Image Quality Enhancement Part VII, LNCS Volume 15966: Trustworthy and Responsible AI for Medical Imaging Part VIII, LNCS Volume 15967: Multimodal Learning for Diagnosis, Risk Prediction, and Survival Analysis Part IX, LNCS Volume 15968: Core Techniques in Medical Imaging: Segmentation, Registration, Synthesis, Reconstruction, and Other Emerging Methods (I) Part X, LNCS Volume 15969: Core Techniques in Medical Imaging: Segmentation, Registration, Synthesis, Reconstruction, and Other Emerging Methods (II) Part XI, LNCS Volume 15970: Core Techniques in Medical Imaging: Segmentation, Registration, Synthesis, Reconstruction, and Other Emerging Methods (III) Part XII, LNCS Volume 15971: Core Techniques in Medical Imaging: Segmentation, Registration, Synthesis, Reconstruction, and Other Emerging Methods (IV) Part XIII, LNCS Volume 15972: Adapting Foundation Models for Medical Imaging: LLMs, VLMs, and Cross-Domain Generalization (I) Part XIV, LNCS Volume 15973: Adapting Foundation Models for Medical Imaging: LLMs, VLMs, and Cross-Domain Generalization (II) Part XV, LNCS Volume 15974: Adapting Foundation Models for Medical Imaging: LLMs, VLMs, and Cross-Domain Generalization (III) Part XVI, LNCS Volume 15975: Statistical Techniques in Medical Imaging: Causality, Imputation, Weak Supervision, and Other Methods

Research Trends in Multidisciplinary subjects - Volume 2 Sruthi.S, Dr.D. David Winster Praveenraj, *Artificial Intelligence in the Age of Neural Networks and Brain Computing* Robert Kozma, Cesare Alippi, Yoonsuck Choe, Francesco Carlo Morabito, 2023-10-11 *Artificial Intelligence in the Age of Neural Networks and Brain Computing*,

Second Edition demonstrates that present disruptive implications and applications of AI is a development of the unique attributes of neural networks, mainly machine learning, distributed architectures, massive parallel processing, black-box inference, intrinsic nonlinearity, and smart autonomous search engines. The book covers the major basic ideas of brain-like computing behind AI, provides a framework to deep learning, and launches novel and intriguing paradigms as possible future alternatives. The present success of AI-based commercial products proposed by top industry leaders, such as Google, IBM, Microsoft, Intel, and Amazon, can be interpreted using the perspective presented in this book by viewing the co-existence of a successful synergism among what is referred to as computational intelligence, natural intelligence, brain computing, and neural engineering. The new edition has been updated to include major new advances in the field, including many new chapters. - Developed from the 30th anniversary of the International Neural Network Society (INNS) and the 2017 International Joint Conference on Neural Networks (IJCNN - Authored by top experts, global field pioneers, and researchers working on cutting-edge applications in signal processing, speech recognition, games, adaptive control and decision-making - Edited by high-level academics and researchers in intelligent systems and neural networks - Includes all new chapters, including topics such as Frontiers in Recurrent Neural Network Research; Big Science, Team Science, Open Science for Neuroscience; A Model-Based Approach for Bridging Scales of Cortical Activity; A Cognitive Architecture for Object Recognition in Video; How Brain Architecture Leads to Abstract Thought; Deep Learning-Based Speech Separation and Advances in AI, Neural Networks

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Special Issue on Adaptive Learning Systems in Communication Networks Alexander G. Parlos,2005

Neural Computation ,2002

Proceedings of the IASTED International Conference, Artificial Intelligence and Soft Computing, July 27 to August 1 1997, Banff, Canada M. H. Hamza,International Association of Science and Technology for Development,1997

Progress in Connectionist-based Information Systems ,1998 These two volumes consist of about 350 papers in three main areas of artificial intelligence and neurocomputing, namely: (1) modelling the brain; (2) methods of soft computing; (3) applications of intelligent information systems. The materials, contained in two volumes, emphasise the importance of connectionist-based information systems which use neural networks and other methods to achieve intelligent information processing, such as speech recognition and language understanding, pattern recognition, vision, learning and adaptation, planning, and decision making. Some of the methods of the connectionist-based information systems directly model the physical organisation of the human brain, which is the area of brain-like computing. Other methods model cognitive aspects of human behaviours, which is the area of cognitive engineering. A third group of methods are based on statistical and probability theory. All these methods are presented and applied on concrete problems. Many connectionist-based systems are

described in different papers of the two volumes. These two volumes are a comprehensive and up-to-date guide to the diverse topics of neuro-computing, artificial intelligence and knowledge engineering.

Sensor Fusion: Architectures, Algorithms, and Applications, 2000

Canadian Journal of Civil Engineering, 1999

Archives of Electrical Engineering, 2004

Introduction to Intelligent and Autonomous Control Panos J. Antsaklis, Kevin M. Passino, 1993 The area of intelligent control is a fusion of a number of research areas in engineering computer science and mathematics, which has evolved from conventional control to enhance the existing nonlinear, optimal, adaptive and stochastic control methods. Intelligent control techniques are currently being utilized for closed-loop feedback control in space-based applications, manufacturing systems, robotic systems, avionic systems, among others, to improve system performance, reliability and efficiency. Overall, the primary objective of intelligent control is to enhance the performance of the system to the extent that it achieves some level of autonomous control.

Principles of Neurocomputing for Science and Engineering Fredric M. Ham, Ivica Kostanic, 2000 Neurocomputing can be applied to problems such as pattern recognition, optimization, event classification, control and identification of nonlinear systems, and statistical analysis - just to name a few. This book is intended for a course in neural networks.--BOOK JACKET.

IJCAI-05 Leslie Pack Kaelbling, 2005

Journal of the Institution of Electronics and Telecommunication Engineers, 1996

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